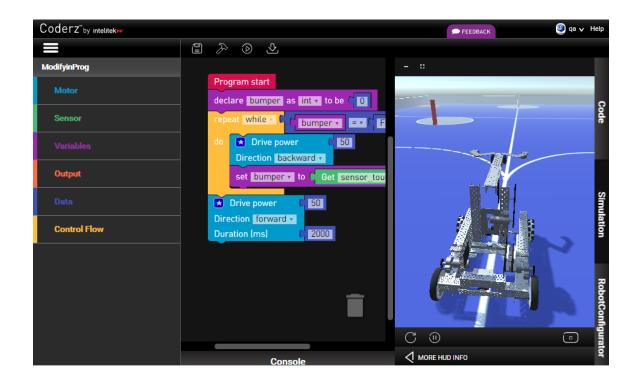
Coderz[™] User Guide



January 2016

Catalog #200079 Rev. A



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Intelitek Professional Development User Guide

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1. Introduction

Coderz is a tool for programming physical and virtual robots using either its Blocks visual programming interface, or via Java.

This document is structured as follows:

Section	Description
1. Introduction	Introduces the document.
2. Users	Explains how to create an account in Coderz and how to change your profile.
3. Home Interface	Describes the Coderz Home interface.
4. Managing Projects	Describes how to create, open, rename, delete and download projects.
5. Blocks Interface	Describes the Blocks interface, how to write Blocks programs and the function of each block.
6. Code Interface	Describes the Code interface, lists the commonly used functions and includes sample programs.
7. Project Interface Panes	Describes the Simulation, RobotConfigurator and Console panes that are common for all project interfaces.
8. Running a Program on a Robot	Describes the process of running a program on a robot.
9. Classes	Describes how to create and manage student classes.



2. Users

In order to use Coderz you must be a registered user.

There are two types of users in Coderz, students and teachers. Teacher accounts have an additional Classes feature, in which they can create and monitor classes, and add students to a class. For more information, refer to section 9.2 Managing a Class.

This section describes the following:

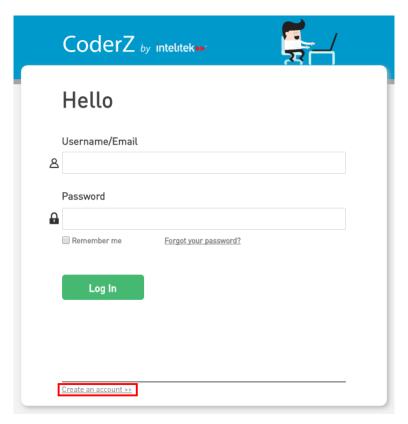
- Creating a Teacher Account
- Creating a Student AccountCreating a Student Account

2.1.1. Creating a Teacher Account

In order to complete the process of creating a Teacher account, you will need the product code that you received from Intelitek. The product key will allow you to add a number of student accounts according to the license that you purchased from Intelitek.

To create a Teacher account in Coderz:

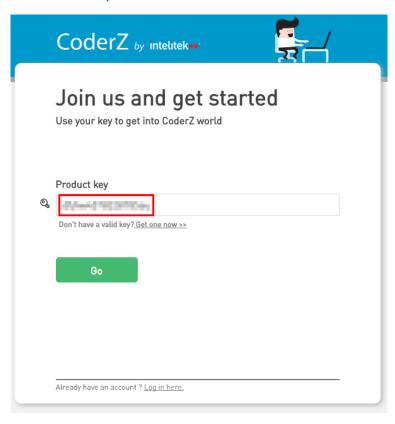
- 1. Navigate to http://ftc.coderzworld.com/.
- 2. Click Create an Account >>.



The Product Key page appears.

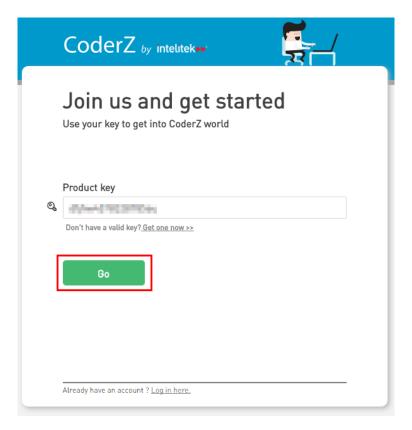


3. Type your Coderz Product key.





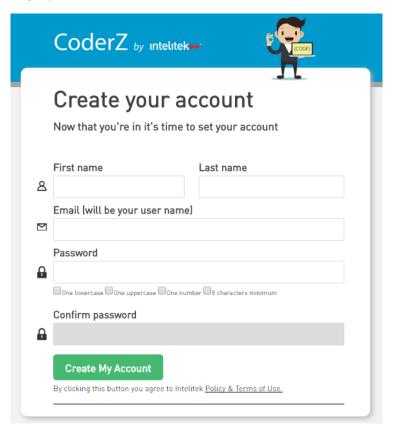
4. Click Go.



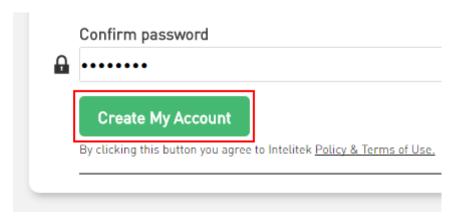
The Signup form appears.



5. Complete the signup form.

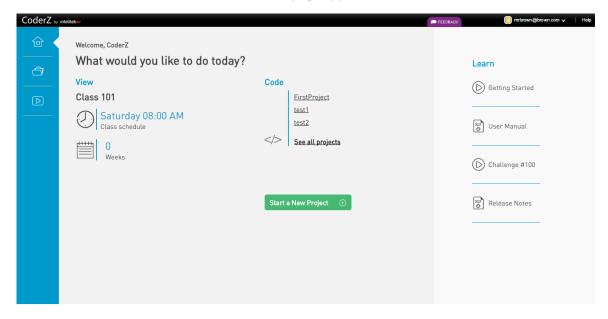


6. Click Create My Account.





Your account is created and the Welcome page appears.



2.1.2. Creating a Student Account

Once a student has been added by a teacher to a class, an email is sent to the student with instructions and a link. The student needs to follow the link and complete the form in order to complete the process of creating their account.

To create a Student account in Coderz:

1. In the "Coderz: Join class invitation" email you received, click **Sign me up!**. If you did not receive this email, contact your teacher. Your teacher must add you to a class in order to start the process of creating your account.

Join class

Follow the link below to signup:



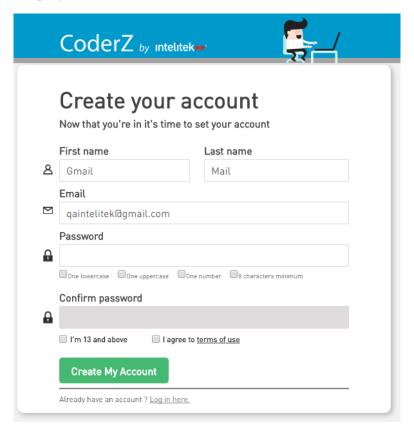
If you didn't request this, please ignore this email.

The CoderZ Team

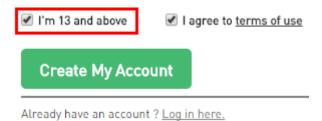
The Create your account page appears.



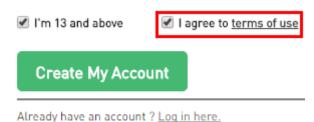
2. Complete the signup form.



3. Select the left checkbox at the bottom of the form to confirm that you are over 13 years of age.

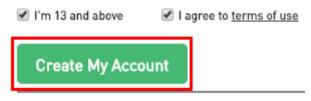


4. Select the right checkbox to agree to the terms of use.



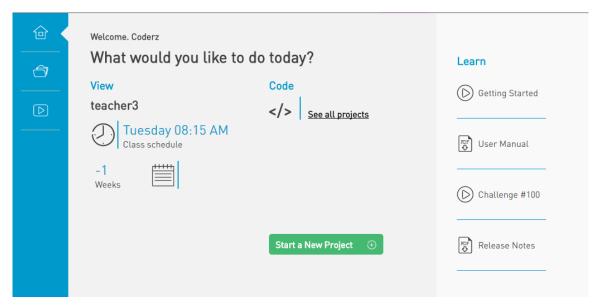


5. Click Create My Account.



Already have an account ? Log in here.

Your account is created and the Welcome page appears.



2.1.3. Profile

The Profile area offers options for changing your profile settings.

To access the Profile area, on the top-right of the Coderz window:

1. Click the arrow beside your username at the top-right of the page.



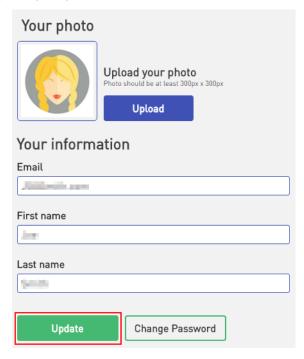


2. Click Profile.



The Profile area is shown.

In the Profile area, you can update your e-mail address, first name, last name and profile picture. Click **Update** to save changes to your profile.



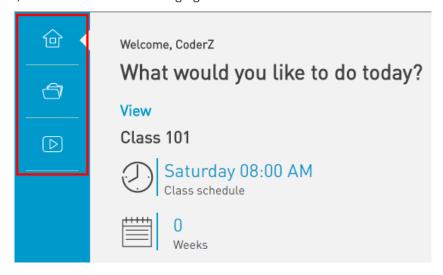


3. Home Interface

Upon logging in to Coderz, the Home interface appears.

3.1. NAVIGATION ICONS

The top-left of the Home interface has three icons. Click these icons to switch between the three Home interface pages. Teacher accounts have an additional Classes icon for accessing the Classes page. For more information, refer to section 9.2 Managing a Class.



The Home interface has the following three pages:

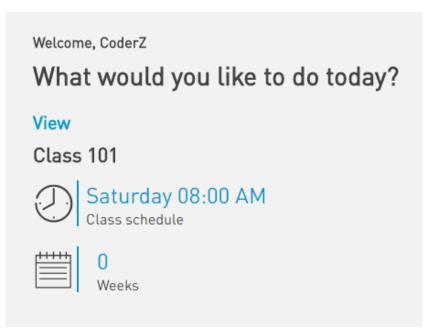
⊕ ◀	Welcome	 The Welcome page contains the following two buttons: Start a New Project. Click this option to open the Project Wizard. For more information, refer to section 4.1 Creating a Project, below. Add a Class. This option is only available for Teacher accounts. Click this option to open the Class Wizard. For more information, refer to section 9.1 Creating a Class, below.
ð	Projects	 The Projects page displays all of your programs. From the Projects page you can: Create a project. For more information, refer to section 4.1 Creating a Project, below. Open a project. For more information, refer to section 4.2 Opening a Project, below. Download a project. For more information, refer to the section 8 Running a Program on a Robot, below.
D	Tutorials	The Tutorials page contains a number of tutorial videos in ascending order of difficulty. These tutorials are designed to help you get started with using and writing programs in Coderz.

3. Home Interface



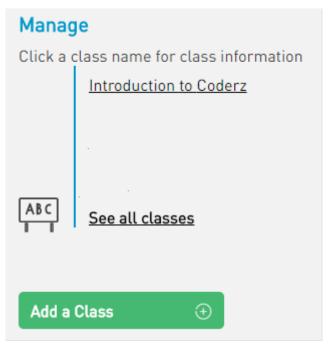
3.2. VIEW AREA

The View area of the Home interface includes information about your class including the schedule and duration.



3.3. MANAGE AREA

The Manage area of the Home interface is only available in Teacher accounts. It provides links to the three most recently opened classes, and an Add a Class button. For more information about creating a class, refer to section 9.1 Creating a Class.



3. Home Interface



3.4. CODE AREA

The Code area of the Home interface provides links to the three most recently opened projects, and a Start a New Project button. For more information about creating a new project, refer to section 4.1 Creating a Project.



3.5. LEARN AREA

The Learn area of the Home interface contains links to the following:

The Learn area of the Floride Interface contains links to the following.		
Getting Started	A YouTube playlist with getting started tutorials for Coderz	
	This Coderz User Guide	
User Manual		
Challenge #100	A YouTube playlist with challenges for Coderz	
Release Notes	Release notes for Coderz	

3. Home Interface



4. Managing Projects

This section describes the following processes for managing projects in Coderz:

- Creating a Project
- Opening a Project
- Renaming a Project
- Deleting a Project

4.1. CREATING A PROJECT

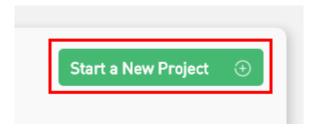
To create a new Coderz project:

- **1.** Either:
 - On the Welcome page of the Home interface, click **Start a New Project**.



or

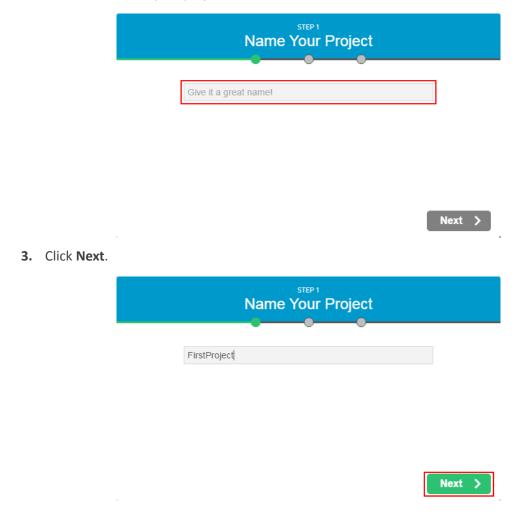
• On the top-right of the Projects page of the Home interface, click **New Project**.



The Project Wizard appears.



2. In the field, name your project.



Step 2 of the Project Wizard appears.



- **4.** Select a method for writing a program for the project. The options here will depend on which version of Coderz you are using.
 - Blocks/Java: A Blocks program is written by dragging and configuring blocks. The code that is written when you add and configure blocks is Java. You do not need to know or use Java for this method.
 - Code: A Code program is written in code using the Java programming language.



5. Click Next.

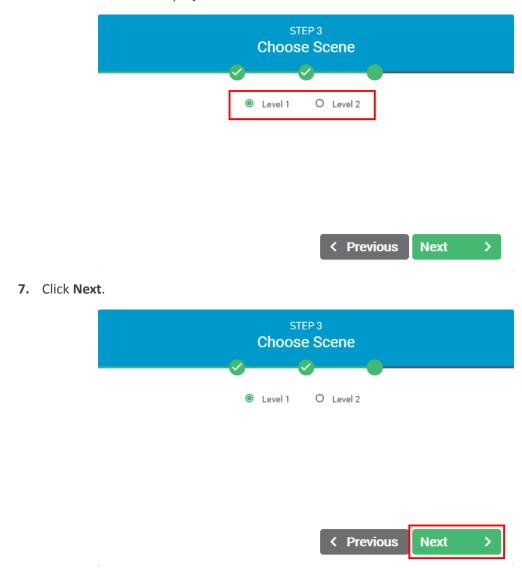


Step 3 of the Project Wizard appears.



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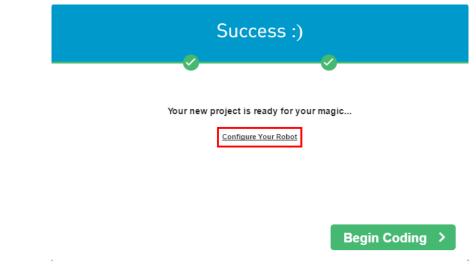
6. Select a scene for the project.



The Success page of the Project Wizard appears.

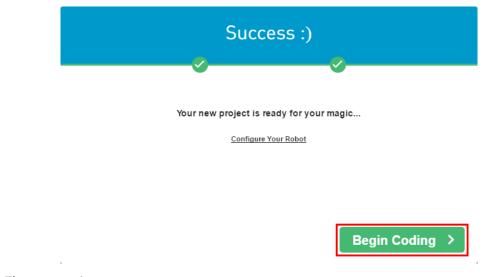


- **8.** The project is created.
 - Click Configure Your Robot to configure the ports for your robot's motors, servos and sensors. The RobotConfigurator appears. For more information, refer to the RobotConfigurator section below.



or

• Click **Begin Coding** to skip robot configuration and open the project.



The new project appears.

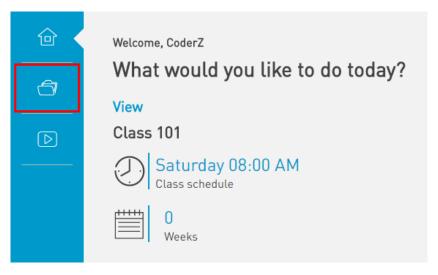


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4.2. OPENING A PROJECT

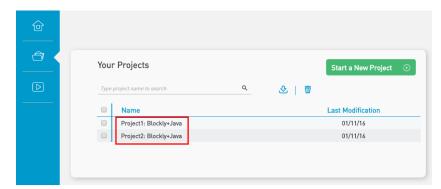
To open an existing project:

1. On the top-right of the Welcome page of the Home interface, click the Projects icor



The Projects page appears.

2. From the Your Projects list, click the name of the desired project.



The project is opened.



4.3. RENAMING A PROJECT

To rename a project:

- 1. If the project you want to rename is not already open, open it as described in section 4.2 Opening a Project, above.
- 2. On the top-left of the project window, hover over the bar that contains the project name.



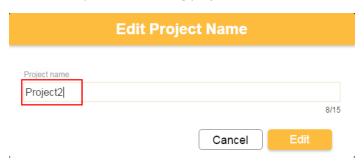
Two icons appear.

3. Click the pencil icon.



The Edit Project Name dialog box appears.

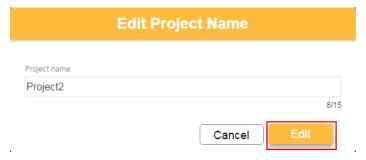
4. In the Project name field, replace the existing project name with another name.



4. Managing Projects



5. Click Edit.



The project is renamed. The new project name appears on the top-left of the project window.



4.4. DELETING A PROJECT

Projects can be deleted from within the open project, or from the Projects page of the Home interface.

4.4.1. Deleting an Open Project

To delete a project:

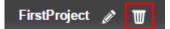
- 1. If the project you want to rename is not already open, open it as described in section 4.2 Opening a Project, above.
- 2. On the top-left of the project window, hover over the bar that contains the project name.



Two icons appear.

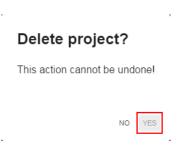
3. Click the trashcan icon.





The Delete project? dialog box appears.

4. Click YES.

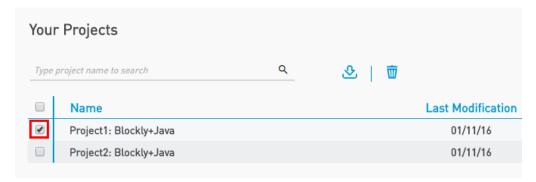


The project is deleted and the Projects page of the Home interface appears.

4.4.2. Deleting a Project from the Projects Page

To delete a project:

1. In the Projects page of the Home interface, select the checkbox for the project or projects that you want to delete.



2. Click the trashcan icon at the top of the page.



The Delete Project dialog box appears.



3. Click **Ok** to delete the project.

If more than one project was selected, a Delete Project dialog box will appear for each project.



5. Blocks Interface

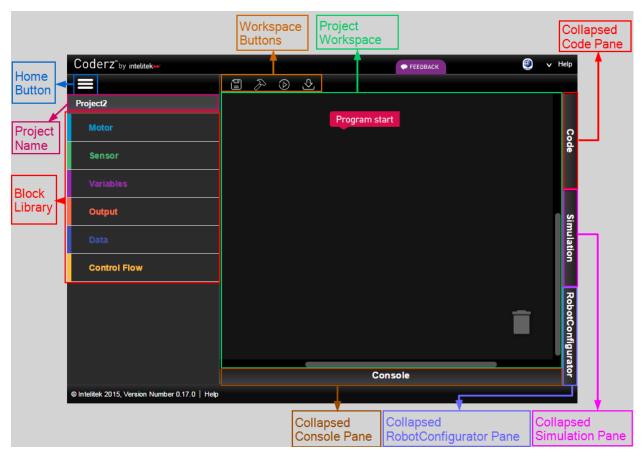
The Blocks interface offers the ability to write visual programs for controlling a robot.

This section introduces the Blocks interface and explains how to write programs using the Blocks method.

This section describes the following:

- Overview
- Adding Blocks
- Configuring Blocks
- Dragging Blocks
- Deleting Blocks
- Comments
- Context Options
- Block Library
- Code Pane

5.1. OVERVIEW



This section describes the elements of the Blocks interface. Refer to the image above for the location of these elements.



The Blocks interface contains the following elements:

Name	Description
Home Button	Click the home button to return to the Welcome page of the Home interface.
Project Name	Displays the project name. Hover over the Project Name area to display the trashcan and pencil icons for deleting and renaming the project. For more information, refer to section 4.3 Renaming a Project and section 4.4 Deleting a Project above.
Block Library	Contains blocks for writing a program, divided by category. Click a category to display its blocks. Drag blocks from the Blocks Library to the Project Workspace to write your program. For more information, refer to section 5.2 Adding Blocks, below.
Workspace Buttons	The following Workspace buttons are above the Project Workspace:
	Save: Saves the open project.
	Compile: Compiles the program, meaning that the program is checked, prepared and packaged so that it can be run on the robot. After clicking this button, the Console is displayed with information about compilation. If there are problems with the program, details of the problems are written to the console. If there are no problems with the program, a success message is written to the console.
	Run Simulation: Compiles the program and runs it in simulation. After clicking this button, the Simulation Pane expands and the simulated robot runs the program.
	Download to Robot: Downloads the program to a physical robot. The robot must be connected via a USB cable to the PC. For more information, refer to section Running a Program on a Robot, below.
Project Workspace	Programs are written in the Project Workspace. Drag blocks from the Blocks Library to the Project Workspace to write your program. For more information on building programs in the Project Workspace, refer to the following sections.
Collapsed Code Pane	Expands the Code Pane. The Code pane displays the code behind the Blocks programs that you write. Any changes made in a Blocks program will dynamically change the code in the Code Pane.

5. Blocks Interface



Name	Description
Collapsed Simulation Pane	Expands the Simulation pane. The Simulation Pane contains a simulation of the robot as configured in the RobotConfigurator that can run programs. For more information, refer to section 7.1 Simulation, below.
Collapsed RobotConfigurator Pane	Expands the RobotConfigurator Pane . In this pane you can configure your robot and its ports. For more information, refer to section 7.2 RobotConfigurator, below.
Collapsed Console Pane	Expands the Console Pane. Program information including compilation details and program running details is written to the console. For more information, refer to section 7.3 Console, below.

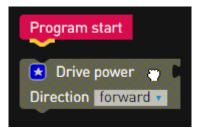
5.2. ADDING BLOCKS

Blocks programs are written by adding blocks to the program in the Program area, and configuring them.

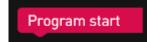
All program blocks must be attached to one another. If a block is not attached to the other blocks in a program, the block will be grayed out, indicating that it is disabled, and will be ignored when running the program.



Blocks have puzzle piece connectors. The shape of each block indicates which type of other block it can be connected to. When the connector of a block is dragged near to the connector of a compatible block, the connector of the block in the program is highlighted, indicating that the dragged block can be released and added to the program.



The first block in a program must be attached immediately below the Program start block that is included automatically in a new project.

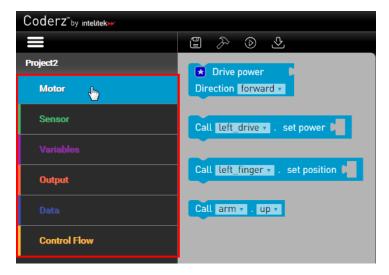




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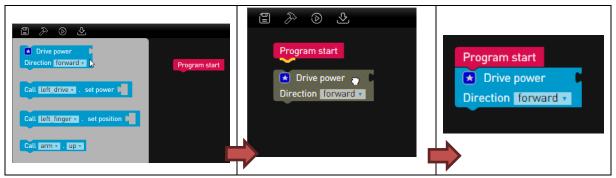
To add a block:

1. In the Block Library, click a Category to expand it.



A gray extension of the Blocks Library that contains the category's blocks appears.

2. Click and drag a block into the program in the Program Workspace.



The block must be attached below or beside, or inserted into a compatible block in the program.

3. Release the block when the connector of the block that you are attaching the dragged block to is highlighted, indicating that it is compatible.

The block is added to the program.

5.3. CONFIGURING BLOCKS

Many blocks require configuration for them to serve their intended command in the program. Different blocks require different configuration. This section describes the configuration of the different types of blocks.



5.3.1. Text Input

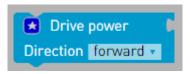
Some blocks require text input. Examples include the number and text blocks shown below.



Click in the field and type a value to add text or a number.

5.3.2. Drop-down Menu

Some blocks contain a drop-down menu, for example the Drive block shown below.



Click the drop-down menu and select an option as required.

5.3.3. Blue Star

There are two blocks that contain a blue star icon that allow you to add additional parameters to the basic block or remove them.

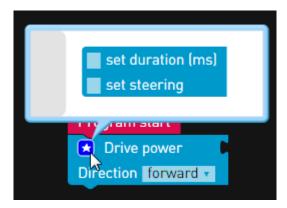
5.3.3.1. Drive Block

The Drive block has a blue star icon that allows you to set the duration or steering for the robot to drive.

To configure the duration or steering of the Drive block:

1. Click the Drive block's blue star icon.

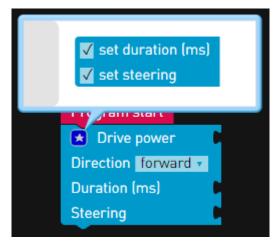
A pop-up window appears.



2. Select the desired options that you want to add to the block.



The options are dynamically added to the block.



3. Click the blue star icon to close the pop-up window.

Repeat steps 1 and 2 and deselect the options to remove them from the block.

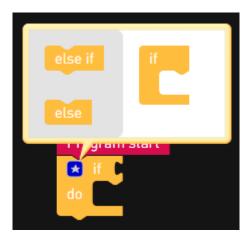
5.3.3.2. If..Do

The If..Do block allows you to create conditions in your program. For example, using this block you can introduce the statement, "If the right optical distance sensor detects a value of 100, drive straight," into your program. The block has a blue star icon that also allows you to add else or else if conditions to the block.

To add conditions to the If. Do block:

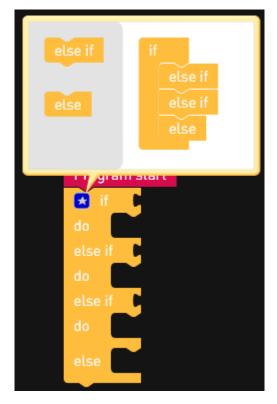
1. Click the If..Do block's blue star icon.

A pop-up window appears.



2. Click either an else if block or an else block in the left gray area of the pop-up window, and drag and release it in place in the block on the right white area of the pop-up window. The conditions are dynamically added to the block. You may add several conditions.





Click an else if or else block from the right white area of the pop-up window and drag and release it in the left gray area of the pop-up window to remove it from the block.

3. Click the blue star icon to close the pop-up window.

5.4. DRAGGING BLOCKS

Click and drag a block to move it within a program.

Clicking and dragging a block that is not the last block will drag all connected blocks that are attached below and beside it.





5.5. DELETING BLOCKS

There are two ways to delete blocks as described in the following subsections.

5.5.1. Trashcan

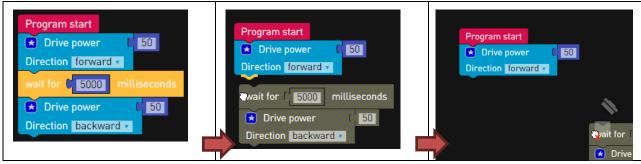
5.5.1.1. Deleting a Single Block

Drag a block onto the trashcan and release it to delete the block.



5.5.1.2. Deleting a Group of Blocks

Drag a block that has connected blocks below or beside it to the trashcan to delete all dragged block.



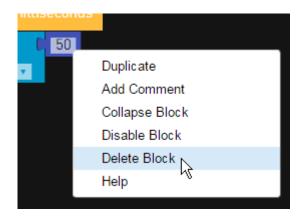
5.5.2. Context Menu

Right-clicking a block opens a context menu, whose options will depend on the block clicked.

5.5.2.1. Deleting a Single Block

To delete a block using its context menu:

- 1. Right-click a block.
- 2. Click Delete Block.



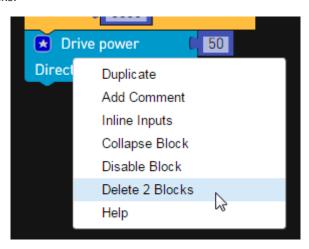


The block is deleted.

5.5.2.2. Deleting a Group of Blocks

To delete a group of blocks using a context menu:

- 1. Right-click a block that has one or more block connected horizontally.
- 2. Click Delete 2 blocks.



The group of blocks is deleted.

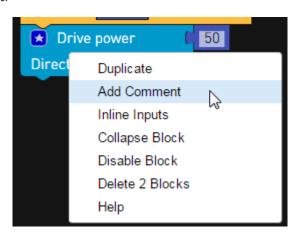
5.6. COMMENTS

Adding comments to a program is good practice and very useful for explaining the program to others, or reminding yourself of the purpose of how the program works.

5.6.1. Adding a Comment

To add a comment to a block:

- 1. Right click a block.
- 2. Click Add Comment.

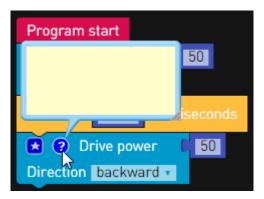


A Comment icon is added to the block.

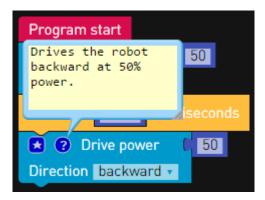


3. Click the Comment icon.

A pop-up window appears. in which you can add comments to the block.



- 4. Click in the pop-up window.
- **5.** Type a comment.



6. Click the Comment icon again.

The comment pop-up is closed.

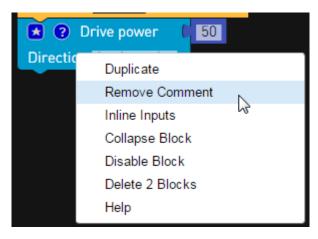
You can view the comment again by clicking the <a> Comment icon.

5.6.2. Removing a Comment

To remove a comment:

- 1. Right-click a block that has a comment.
- 2. Click Remove Comment.

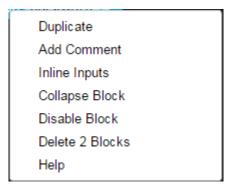




The comment is removed.

5.7. CONTEXT OPTIONS

This section describes the options in a context menu that are displayed when right-clicking a block.



5.7.1. Duplicate

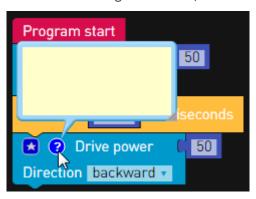
Click **Duplicate** to duplicate a block and all those horizontally connected to the block that you right-clicked.



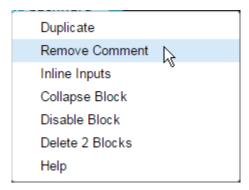
5.7.2. Add Comment / Remove Comment

Click **Comment** to add a **Comment** icon to the block.

Click the Comment icon to display a pop-up window in which you can add comments to the block. For more information, refer to section 5.6.1 Adding a Comment, above.



When a block has a Comment, the block's context menu has a Remove Comment option instead. Click Remove Comment to delete the comment.



For more information, refer to section 5.6.2 Removing a Comment, above.

5.7.3. Inline Inputs / External Inputs

This option allows you to toggle the appearance of a block to one of the following:

• Inline Inputs (default for most blocks): Input blocks, such as data, are set within the block.



• External Inputs: Input blocks stick to the right end of the block.

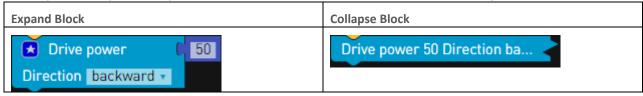


Your code is not affected when changing to or from either of these two configurations. The changes are purely aesthetic and allow you to modify the appearance of the code so that it is easier to understand.



5.7.4. Collapse Block / Expand Block

This option collapses or expands the current block and those that are horizontally attached.



It is useful to collapse blocks when a program is long and difficult to read. Collapsing blocks shortens a program so that it is easier to read and see the entire program. On the other hand, while blocks are collapsed, information is hidden.

The context menu option changes depending on the current setting.

5.7.5. Disable Block / Enable Block

This option disables or enables the current block and those that are horizontally attached.



Disabled blocks are ignored by the program. Instead of deleting blocks that you do not want but may need later, you can disable them and enable them when needed.

The context menu option changes depending on the current setting.

5.7.6. Delete Block

Click **Delete Block** to delete a block and those that are horizontally attached. For more information, refer to section 5.5 Deleting Blocks, above.

5.7.7. Help

Click **Help** to display information about the block and an example program that uses the block.



5.8. BLOCK LIBRARY

The Block Library contains the blocks that are used to write programs, divided by category. This section describes each block.

ⓐ Note: Available blocks in your interface depend on your robot's configuration.

5.8.1. Motor Blocks

Block	Description	Configuration
Prive power 2	Drives a robot (rotates both motors).	1. Click the blue star icon to add additional parameters:
Direction forward 3	motors).	 Duration: How long the robot should drive for (milliseconds). Steering: The steering value for the drive. 0 drives the robot straight. A positive number turns the motor to the right. A negative number turns the robot to the left. The greater the magnitude of the number, the shorter the turn radius. The turn radius is also dependent on the drive power.
		For more information, refer to section 5.3.3.1 Drive Block, above. 2. Add a number block to define the power (%) for the robot to drive at. A value of 100 rotates the wheel motors at full speed. 3. Select the direction to drive in (forward/backward).
Call left_drive . set power . 2	Rotates a single motor.	 Select which motor to rotate. Add a number block to define the power (%) for motor rotation.
Call left_finger v . set position 2	Sets the position of a servo. Servos are motors that can be set at specific rotation angles. They are used to control the gripper.	 Select which servo to control. Each servo controls one of the gripper fingers. Add a number block to define the position to move the servo to.
Call arm v. up v	Raises or lowers an armMotor.	 Select which armMotor to control. Select either up or down.



5.8.2. Sensor Blocks

Block	Description	Configuration
Get ultrasonic to distance in inches 2	Returns the distance of an object in front of the robot's ultrasonic distance sensor.	 Select the ultrasonic sensor to check. Select whether to detect distance in inches or meters.
Get bottom_left_ods . getIntensity	Returns the light intensity detected by the robot's light sensor or Optical Distance Sensor.	1. Select the sensor to check.
Get Color red 2	Returns "1" if the defined color is detected, or False"0" if it is not.	 Select the color sensor to check. Select the color to check.
Call Color v. enableLed v	Enables or disables the LED on a color sensor.	 Select the color sensor to check. Select enableLed to enable the LED or disableLed to disable it.
Get sensor_touch v . getState	Returns the state of the robot's bumper switch or touch sensor (pressed/not pressed).	Select the bumper switch or touch sensor to check.
Get Gyro v . getAngle v 2	Returns: • the angle of the robot's gyro, relative to its position when the program started. The angle continues past 360° or -360° infinitely. • the rate at which the angle of the gyro changes.	 Select the gyro to check. Select getAngle to check the angle of the robot's gyro, relative to its position when the program started or getRate to check the rate at which the angle changes.



Block	Description	Configuration
Call gyro v. reset	Resets the value of a sensor.	1. Select the sensor to reset.
Get Gyro v. getValue	Returns the value of a sensor.	1. Select the sensor to check.

5.8.3. Variables Blocks

A variable is like a placeholder for a value of some sort. This value may be changed.

Block	Description	Configuration
vary	Calls a variable.	1. Select which variable to call.
declare var as int v to be 1 2 3	Creates a variable.	 Define a name for the variable. Select the variable type (int, float, String, bool). Insert a number block to define the value for the variable.
set vary to 12	Changes the value of a variable.	 Select the variable to change. Insert a number block to define a new value for the variable.

5.8.4. Output Blocks

Block	Description	Configuration
print 1	Prints a message to the top line of the robot's LCD display.	Add a text or number block. Its contents will be printed to the robot's LCD display.

5.8.5. Data Blocks

Block	Description	Configuration
	Contains a number.	Type a numerical value. The value can be any real number including negative or rational numbers.
1	Contains text.	1. Type text in the field.
True	Represents a Boolean value (True/False).	1. Select True or False.



Block	Description	Configuration
1 2 3	Performs a mathematical operation between two numbers.	 Insert a number block. Select an operation (addition, subtraction, multiplication, exponentiation). Insert a number block.
123	Checks the relationship between two numbers and returns a Boolean value.	 Insert a number block. Select a relationship to check (equal, not equal, less than, less than or equal to, more than, more than or equal to). Insert a number block.
not	Negates a number.	Add a number block. The result of the two blocks together is the negative value of the number block.
1 2 3	Checks two conditions and returns a Boolean value.	 Insert a number block. Select the conditions (and, or, not, exclusive or). Insert a number block.
square root	Performs a square root operation.	1. Insert a number block. The result of the two blocks is the square root of the number block.
base power power 2	Performs exponentiation.	 Insert a number block for the base. Insert a number block for the exponent.
abs t	Returns the absolute value of a number.	1. Insert a number block.
Random in Range	Returns a random number between 0 and the inserted number block.	Insert a number block to define the maximum possible value for the random number.

5.8.6. Control Flow Blocks

Block	Description	Configuration
repeat times do 2	Repeats a single block or multiple blocks in a loop a defined number of times.	 Insert a number block to define the number of times to repeat the loop. Insert a single block or multiple blocks to repeat in a loop.



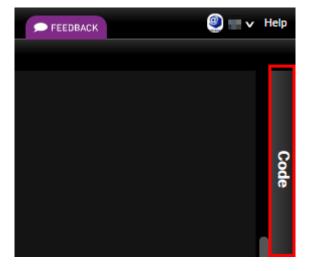
Block	Description	Configuration
repeat while v do 3	Repeats a single block or multiple blocks in a loop while or until a condition is true.	 Select while to repeat the loop while a condition is true, or until to repeat the loop while the condition is false. Add a condition to check. Insert a single block or multiple blocks to repeat in a loop.
if 1 do 2	Repeats a single block or multiple blocks in a loop if a condition is true. Alternate conditions can be added as described in section 5.3.3.2 lfDo, above.	 Add a condition to check. Insert a single block or multiple blocks to repeat in a loop.
wait for milliseconds	Pauses program execution for a defined time. This block does not affect the robots current behavior. It pauses the program from continuing to execute the next commands until the defined time has expired.	Insert a number block for the time (milliseconds) to pause.

5.9. CODE PANE

The Code pane displays the code behind the Blocks program that you write. Any changes made in a Blocks program will dynamically change the code in the Code Pane.

5.9.1. Expanding the Code Pane

To expand the Code pane, on the top-right of the Blocks interface, click the collapsed Code pane.



5.9.2. Collapsing the Code Pane

To collapse the Code pane, click one of the following:

• The Code pane minimize button.



```
package code;

package code;

import com.intelitek.coderz.*;

public class MyOpModeRegister implements OpModeRegiste @Override
public void register(OpModeManager opModeManager)
opModeManager.register("MyOpMode", new MyOpMode
```

or

• The Code bar.

```
- :

1
2 package code;
3
4 import com.intelitek.coderz.*;
5
6 public class MyOpModeRegister implements OpModeRegist
7 @Override
8 public void register(OpModeManager opModeManager)
9 opModeManager.register("MyOpMode", new MyOpMode")
```

5.9.3. Maximizing / Restoring the Code Pane

The Code pane can be maximized. Doing so hides the Project Workspace area completely.

To maximize the Code pane, click the Full Screen button.

```
package code;

import com.intelitek.coderz.*;

public class MyOpModeRegister implements OpModeRegiste

public void register(OpModeManager opModeManager)

opModeManager.register("MyOpMode", new MyOpModeManager)
```

To restore the Code pane to its original width, click the Full Screen button again.

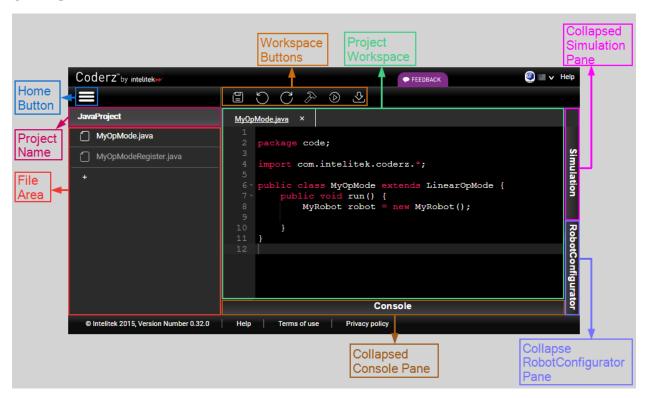


6. Code Interface

This section describes the following:

- Overview
- Managing Files
- Commenting
- Search
- Autocomplete
- Java Commonly Used Functions
- Java Sample Programs

6.1. OVERVIEW



This section describes the elements of the code interface. Refer to the image above for the location of these elements.

The code interface contains the following elements:

Name	Description
Home Button	Click the home button to return to the Welcome page of the Home interface.



Name	Description
Project Name	The name of the project is displayed in the Project Name area. Hover over the Project Name area to display the trashcan and pencil icons for deleting and renaming the project. For more information, refer to section 4.3 Renaming a Project and section 4.4 Deleting a Project above.
File Area	The File area contains all programs in the project.
Workspace Buttons	The following Workspace buttons are above the Project Workspace: Save: Saves the open project.
	Undo: Undoes an action.
	Redo: Redoes an action that was undone.
	Compile: Compiles the program. After clicking this button, the Console is displayed with information about compilation. If there are problems with the program, details of the problems are written to the console. If there are no problems with the program, a success message is written to the console.
	Run Simulation: Compiles the program and runs it in simulation. After clicking this button, the Simulation Pane expands and the simulated robot runs the program.
	Download to Robot: Downloads the program to a physical robot. The robot must be connected via a USB cable to the PC. For more information, refer to section Running a Program on a Robot, below.
Project Workspace	Programs are written in the Project Workspace.
Collapsed Simulation Pane	Expands the Simulation pane. The Simulation Pane contains a simulation of the robot as configured in the RobotConfigurator that can run programs. For more information, refer to section 7.1 Simulation, below.
Collapsed RobotConfigurator Pane	Expands the RobotConfigurator Pane. In this pane you can configure your robot and its ports. For more information, refer to section 7.2 RobotConfigurator, below.
Collapsed Console Pane	Expands the Console Pane. Program information including compilation details and program running details is written to the console. For more information, refer to section 7.3 Console, below.

6. Code Interface



6.2. MANAGING FILES

A Java project can contain multiple files.

Project files appear as a list in the File Area.

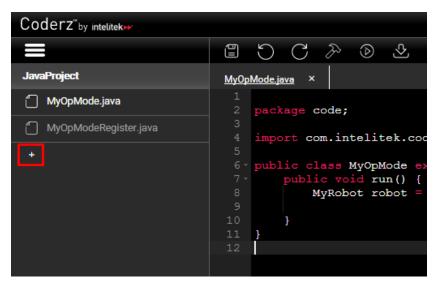
This section describes the following:

- Adding Files
- Renaming a File
- Opening/Closing a File
- Deleting a File

6.2.1. Adding Files

To add a file to a project:

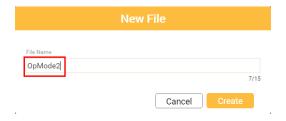
1. Below the list of existing files in the File Area, click the **+** icon.



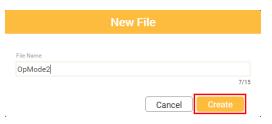
The New File dialog box appears.



2. In the File Name field, name the file.



3. Click Create.



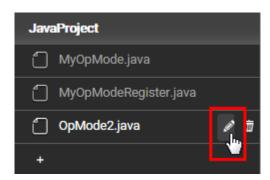
The file is created and the new .java file appears in the File Area.



6.2.2. Renaming a File

To rename a file:

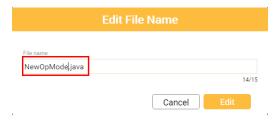
1. In the File Area, hover over the filename and click the pencil icon.



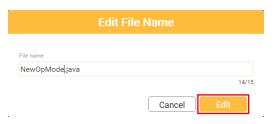
The Edit File Name dialog box appears.



2. In the File name field, rename the file.



3. Click Edit.



The file is renamed.

6.2.3. Opening/Closing a File

Open files appear as tabs at the top of the Project Workspace.

To open a file, in the File Area click the name of a file.



To close a file, on the file's tab, click the x.

```
MyOpMode.java × NewOpMode.java ×

1
2 package code;
3
4 import com.intelitek.coderz.*;
5
6 public class OpMode2 {
```

6. Code Interface 46



6.2.4. Deleting a File

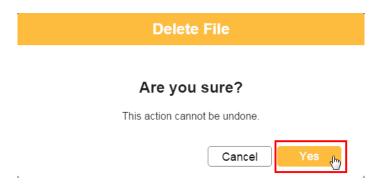
To delete a file:

1. In the File Area, hover over the filename and click the trashcan icon.



The Delete File dialog box appears.

2. Click Yes.



The file is deleted.

6.3. COMMENTING

Adding comments to a program is good practice and very useful for explaining the program to others, or reminding yourself of the purpose of how the program works.

Comments are ignored when the program is executed.

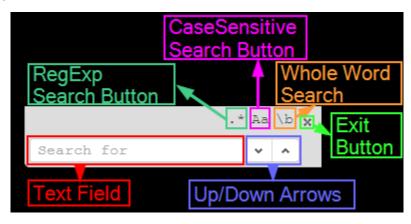
To add a comment, add two forward slashes followed by the comment.



6.4. SEARCH

You can search within the code in the Project Workspace using the Search box. This section describes the Search box and how to search for a String.

6.4.1. Search Box



This section describes the elements of the Search box. Refer to the image above for the location of these elements.

The Search box contains the following elements:

Name	Description
Text Field	In the Text Field, enter the String to search for.
Up/Down Arrows	Click ∨ to search upward in the program or ∧ to search downward.
Exit Button	Click X to close the Search box.
RegExp Search Button	Click the RegExp Search button to allow regular expressions in the search. For example, an asterisk can be used to represent any character.
CaseSensitive Search Button	Click the CaseSensitive Search button to make the search case sensitive.
Whole Word Search	Click the Whole Word Search button to only search for whole words. When enabled, if the search String is part of a word, it will be ignored in a search.

6.4.2. Search for a String

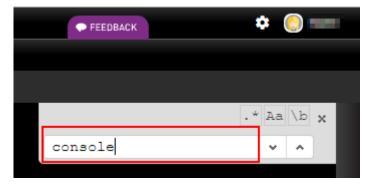
To search for a String:

1. Press Control and F simultaneously.

The Search box appears.

2. Type a search string in the field.





3. Press ∨ to search upward in the program or ∧ to search downward.

6.5. AUTOCOMPLETE

When adding the first of any of the following pairs to a program, the second is automatically added:

- Round brackets: ()
- Braces: { }
- Quotation marks: ""



6.6. JAVA COMMONLY USED FUNCTIONS

This section provides the Java code for commonly used functions.

The full list of the Java functions, parameters and their descriptions for Coderz can be found here: http://ec2-54-213-86-65.us-west-2.compute.amazonaws.com/java-doc/index.html.

The table below shows blocks from the Blocks interface and the equivalent Java code.

Category	Block Function and Parameter Blocks	Equivalent Java Code and Parameters
Motor	Direction forward v	robot.drive(, Direction.Forward);
Motor	Call left_drive ▼ . set power ▶	robot.getLeft_drive().setPower();
Motor	Call left_finger ▼ . set position ▶	robot.getLeft_finger().setPosition();
Motor	Call arm v . up v	robot.getArm().up();
Sensor	Get bottom_left_ods ▼ . getIntensity	robot.getBottom_left_ods().getIntensity()
Sensor	Get sensor_touch ▼ . getState	robot.getSensor_touch().getState()
Variables	Var ▼	var2;
Variables	declare var as int v to be	int var2 = 0;
Variables	set var v to (0	var2 = 0;
Output	print (0	Console.print(0);
Control Flow	repeat 2 times	for (intindex1 = 0;index1 < 2; index1++) { }
Control Flow	repeat while ▼ (True ▼ do	while (true) {}



Control Flow	if .	if () {} else if (false) {} else {}
	do else if	
	do	
	else	

6. Code Interface



6.7. JAVA SAMPLE PROGRAMS

This section provides some sample programs that demonstrate the implementation of some common Coderz Java functions.

Program 1 Description: The state of the robot's Bumper Switch is written to a variable. While the Bumper Switch is not pressed, the robot reverses. **Blocks Program Equivalent Java Program** public void run() { Program start MyRobot robot = new MyRobot(); declare touch as bool v to be (False v boolean touch = false; repeat while v while (true) { repeat while touch ▼ False 🕶 while (touch == false) { 100 ★ Drive power robot.drive(100, Direction backward • Direction.Backward); set touch v to Get sensor touch . getState touch = robot.getSensor_touch().getState(); ▶ Drive power 100 Direction forward • robot.drive(100, Direction.Forward);

6. Code Interface



7. Project Interface Panes

This section describes the panes that are common to all project interfaces.

7.1. SIMULATION

The Simulation Pane contains a simulation of the robot as configured in the RobotConfigurator that can run programs.

7.1.1. Overview



This section describes the elements of the Simulation pane. Refer to the image above for the location of these elements.

The Simulation pane contains the following elements:

Name	Description
HUD Info	Displays sensor values. This area can be shown or hidden by clicking the More/Less HUD Info button.
Collapse Button	Collapses the Simulation pane.
Full Screen Button	Maximizes the Simulation pane and hides the Project Workspace area completely.
	To restore the Simulation pane to its original width, click the Full Screen button again.



Name	Description
Simulator	The Simulator contains the actual simulation of the robot. For information about controlling the Simulator, refer to section 7.1.2 Control, below.
	The Simulator scene can be changed using the RobotConfigurator. For more information, refer to section 7.2.1 Overview, below.
Reset Button	Resets the Simulator.
More/Less HUD Info button	Shows or hides the HUD Info area.
Play/Pause Button	Plays or pauses a program running in the Simulator.
360° Spin Button	Spins the Simulation view around the robot.

7.1.2. Control

This section describes the following control operations in the Simulator:

- Zoom
- Pan
- Reset

7.1.2.1. Zoom

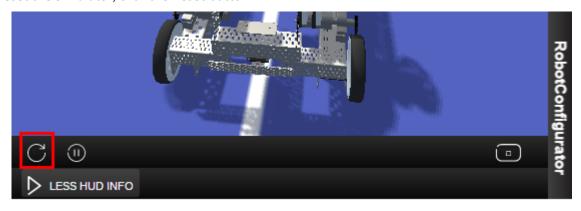
To zoom in or out in the Simulator, with the curser on the Simulator scroll the mouse scroll wheel up and down.

7.1.2.2. Pan

To pan in the Simulator, click in the Simulator and move your mouse around.

7.1.2.3. Reset

To reset the Simulator, click the Reset button.



7.1.3. **HUD Info**

The HUD Info area displays sensor values. It is useful to have the HUD Info area open and to pay attention to the sensor values while a program is running. It can help to fine-tune a program or to check why a program is not running as expected.

To show or hide the HUD Info area, click the More/Less HUD Info button.





7.2. ROBOTCONFIGURATOR

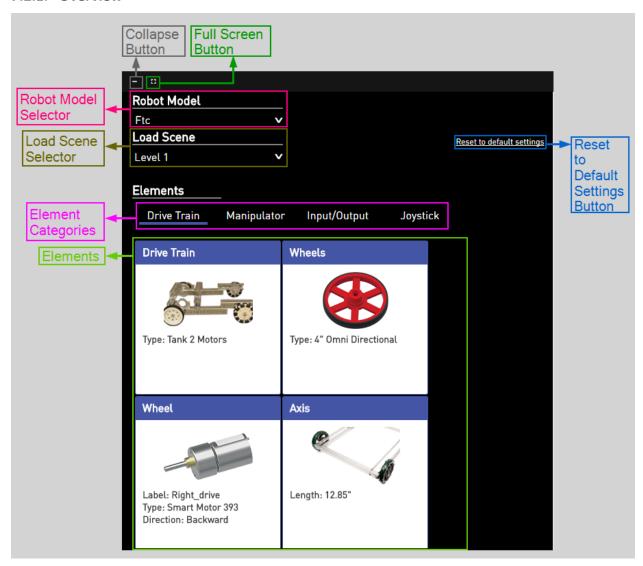
A project must be configured for your physical robot so that the program knows what elements it has and where relevant, what ports they are connected to. You can configure your robot using the RobotConfigurator.

This section describes the following:

- Overview
- Adding an Element
- Editing an Element
- Deleting an Element



7.2.1. Overview



This section describes the elements of the RobotConfigurator pane. Refer to the image above for the location of these elements.

The RobotConfigurator pane contains the following elements:

Name	Description
Collapse Button	Collapses the RobotConfigurator pane.
Full Screen Button	Maximizes the RobotConfigurator pane, while hiding the Project Workspace area completely.
	To restore the RobotConfigurator pane to its original width, click the Full Screen button again.
Robot Model Selector	Select your robot from the robot builds in the drop-down menu.
Load Scene Selector	Select a scene for the Simulation from the scenes in the drop-down menu.
Element Categories	Elements are divided by category. Click a category to display its elements.



Name	Description
Elements	Each Element Category's elements appear when the category name is clicked.
	Some elements have the following icons on the top-right:
	Accelerometer W >
	 Click the trashcan icon to delete the element. Click the pencil icon to configure the element's name and the port that it is connected to.
	Some Element Categories have an icon beside its elements. Click the icon to add a new element.
Reset to Default Settings Button	Resets the configuration to its default.

7.2.2. Adding an Element

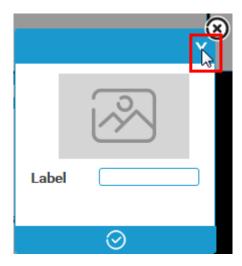
For some Element Categories you can add elements.

To add an element:

1. Click the icon.

The Select element window appears.

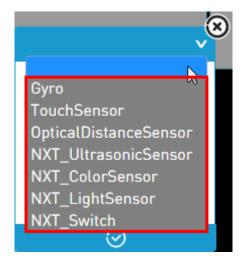
2. Click the Vicon.



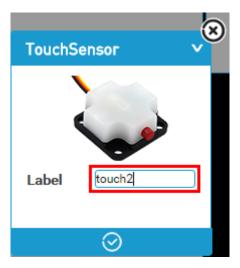
A drop-down list appears.

3. Select an element.

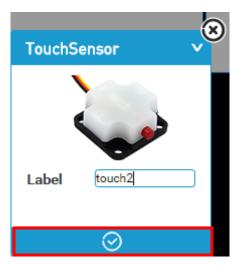




4. In the Label field, name the element.



5. Click the icon



The element is added.



7.2.3. Editing an Element

To edit an element:

1. On the top-right of an element, click the pencil icon.



- 2. Make the required changes to the element.
- 3. Click the icon.



The changes are saved.



7.2.4. Deleting an Element

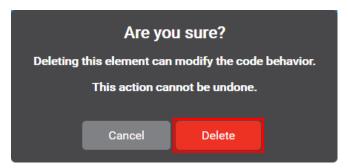
To delete an element:

1. On the top-right of an element, click the trashcan icon.



The Are you sure? dialog box appears.

2. Click Delete to confirm that you want to delete the element.

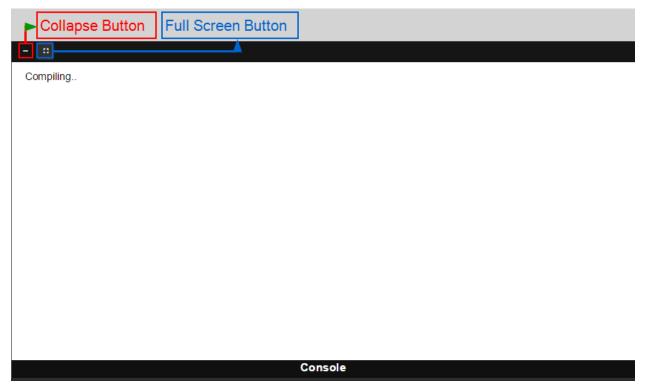


The element is deleted.



7.3. CONSOLE

Program information including compilation details and program running details is written to the console.



This section describes the elements of the Console pane. Refer to the image above for the location of these elements.

The Console pane contains the following elements:

Name	Description
Collapse Button	Collapses the Console pane.
Full Screen Button	Maximizes the Console pane and hides the Project Workspace area completely.
	To restore the Console pane to its original size, click the Full Screen button again.



8. Running a Program on a Robot

Programs can be downloaded to your FTC robot from either of the project interfaces (Blocks, Java). The program is included in an FTC Robot Controller app which is installed on the Robot Controller Android device. Your program can then be run from the Driver Station as described in this section.

The programs will only run on an FTC robot like the one in the Coderz simulation. The robot's configuration will have to match the configuration in the Robot Configurator pane for the project that contains the program.

For information about building an FTC robot and using the FTC Robot Configurator and FTC Device Driver Android devices and apps, refer to the FTC Robot Building Resources: http://www.firstinspires.org/node/5181.

8.1. PREPARING THE ROBOT CONTROLLER ANDROID DEVICE

To install a Robot Controller app with your Coderz program (.apk file), you will first need to change the setting on your Android device to allow installation of non-market applications by selecting the checkbox next to "Unknown Sources" in the following location: Settings > Security or Settings > Security & Screen Lock.



8.2. DOWNLOADING TO A ROBOT

To download a Robot Controller app with your program to a robot:

- 1. If the program you want to run on your robot is not already open, open it.
- 2. Click the Download to Robot button.





Note: The first time you download a program, you will be prompted to download an application called the Robot Downloader. Download and unzip the Zip file, and then run the setup to install the application.

The program compiles and an .apk file is downloaded to your computer.

- **3.** Attach an Android device to your computer with a USB cable.
- **4.** Copy the published .apk file over to the Android device. Make a note of where you move the file to.
- 5. Locate the file using a file explorer and run it to install the app on your Android Device.

8.3. CONFIGURING THE ROBOT

Before running your program, with the Robot Controller app installed and the Robot Controller Android device connected to your robot you must configure the hardware.

Motors and sensors must be named exactly as they are in the properties for their components in App Inventor.





8.4. RUNNING THE PROGRAM

To run the program you must pair the Driver Station Android device with the Robot Controller. Once paired, you will be able to run your program by pressing Select Op Mode and selecting the name of your program.





9. Classes

Teacher accounts have an additional Classes icon on the left of the Home Interface.



Clicking the icon displays the Classes page.

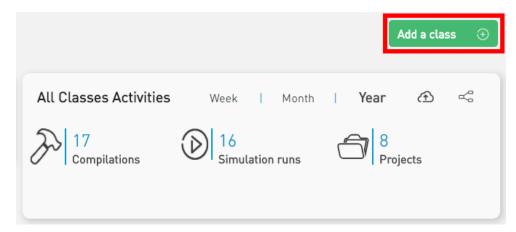
The Classes page contains the following areas:

- Your Classes: Lists your classes. Click a class to see class settings and statistics, details of enrolled students, and to enroll additional students.
- All Classes Activities: Displays global statistics for all of your classes, including the number of compilations, simulations runs and projects across all classes. Statistics can be filtered by week, month or year, and can be exported and shared using the icons on the top-right of the area.

9.1. CREATING A CLASS

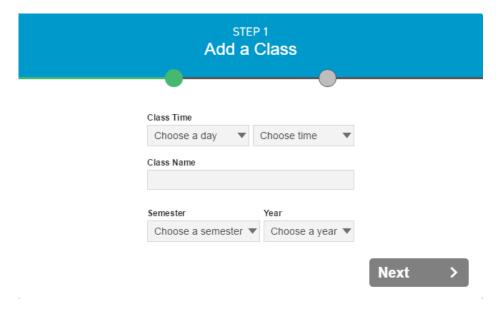
To create a Coderz class:

1. On the Classes page of the Home interface, click Add a Class.

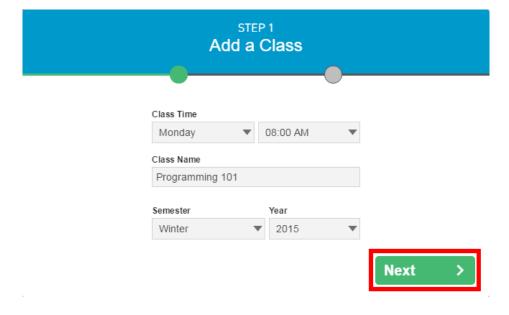


2. Define the time, name, semester and year for the class.



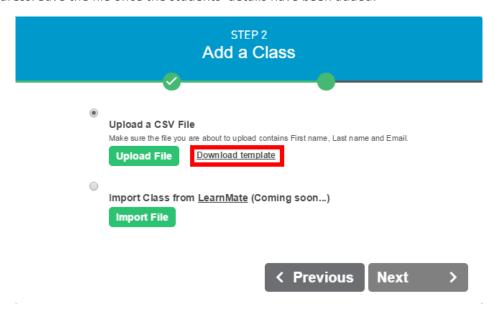


3. Click Next.

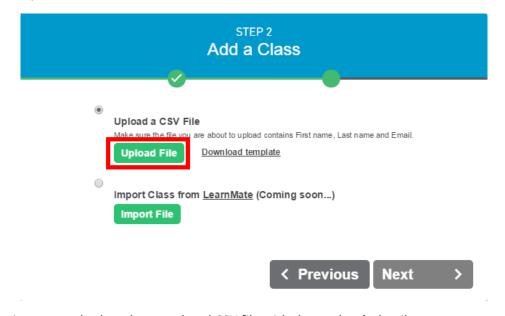




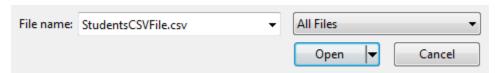
4. If you do not already have a completed CSV file with student details, click **Download template** and add the details for the students that you want to enroll into the course. Each student's details must occupy its own row, and must be in the format: first name, last name, email address. Save the file once the students' details have been added.



5. Click Upload File.

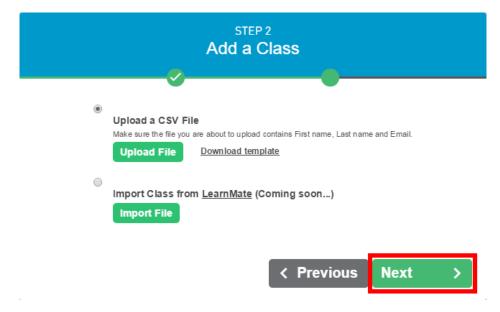


6. Navigate to and select the completed CSV file with the student's details.

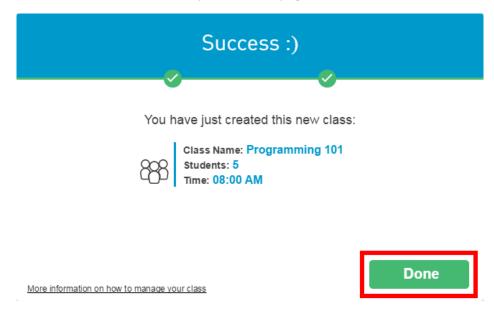




7. Click Next.



8. The class is created. Click **Done** to open the Class page for the new class.

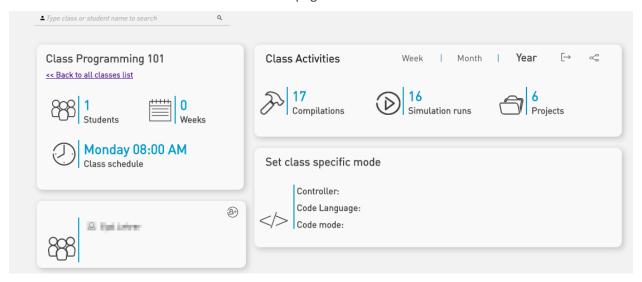




9.2. MANAGING A CLASS

The Class page displays information about a class. You can access a class page by clicking the class name in the Class page of the Home interface.

This section describes the elements of the Class page.



Item	Description
♣ Type class or student name to search Q	Search: Type a student name to search for the student.
Class Programming 101	Class Name: Hover over the class name and click the pencil icon to edit the name.
Students	Number of Students: Hover over the number of students and click the pencil icon to upload a CSV file to add more students to the course.
Monday 08:00 AM Class schedule	Class Schedule: Hover over the class schedule and click the pencil icon to edit the schedule.
a	Add a Student. Click this button to add an individual student to the class.
△ Mr Brown	Student Name: Click a student name to display the student's class activities. These activities can be filtered by day/month/year and can be exported or shared.
The state of the s	Class Activities: Displays class activities. These activities can be filtered by day/month/year and can be exported or shared.
Controller: Code Language: Code mode:	Class Specific Mode: Hover over any of the three items and click the pencil icon to define the controller, code language or code mode for the class.